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Why existing approaches fail.

The need for Unified Intelligence.

This whitepaper is part of a four-part series. The series introduces Unified Intelligence as a new category, explains why 'always-on' intelligence is required to unlock the potential of AI, covers how to adopt the technology and embed it into complex operations, and imagines a world in which Unified Intelligence is ubiquitous.

A worked example.

It is a routine weekday at a major container port. Vessel arrival forecasts are on plan. Berth allocation models are stable. Yard utilisation sits comfortably within limits. Crane productivity is tracking above target. Crew schedules for pilotage and towage appear sufficient, with contingency capacity available.

Every dashboard is green. Every plan is considered robust.

At 09:00, a minor deviation occurs. A vessel due to arrive in twelve hours reduces its steaming speed. This is unremarkable; it happens frequently. The ETA prediction updates automatically, showing a two-hour delay. The vessel will still arrive within its allocated window. The berth plan remains unchanged. From a scheduling perspective, nothing has changed. From the operation's perspective, everything has.

The delayed arrival compresses the pilotage sequence. A four-hour buffer between a departing vessel and the inbound arrival shrinks, quietly removing slack from the schedule. No constraint is breached. No alert is triggered.

As the day progresses, an unrelated event occurs: a crane breakdown reduces productivity on a different berth. The departure of the vessel alongside slips by two hours. This pushes it into direct overlap with the inbound vessel identified earlier. The operation remains viable, but coordination across pilotage and towage is now critical. The margin for error has narrowed.

The disruption is still eight hours away. There is time to intervene. But because the plan remains technically feasible, no changes are made.

Meanwhile, two earlier departures run longer than expected, consuming towage resources for extended periods. Individually, these overruns are inconsequential. Collectively, they begin to form a constraint. This emerges quietly, across the ecosystem, without breaching any single rule or threshold.

By late afternoon, the compounded effect becomes visible. Towage availability is insufficient to support all planned movements. One vessel must now wait until 23:00 to move. As recovery planning begins, a further consequence is uncovered: a late berthing will propagate forward, disrupting an inbound vessel scheduled for the same berth two days later.

Only now does the situation present as systemic. Only now do the decisions become difficult.

At every step, the analytics were correct. The forecasts were accurate. The plan was recalculated as new information emerged. No model was wrong. No tool failed. What failed was the ability to understand how small, reasonable changes interacted over time to reshape the behaviour of the system.

Reality moved. And the tools the operation relied upon were not designed to move with it.

This chapter explicitly explores why existing approaches to decision intelligence fail so often in high-consequence, highly complex, and dynamic operational contexts. It outlines how the problem is not a lack of data or AI. Instead, it's the absence of a continuously maintained operational truth. This chapter follows our first chapter in which we introduce Unified Intelligence as a new category. Its purpose is to bring to life why intelligence must be continuous for it to be operationally effective.



Reality changes.

No plan survives first contact with reality.

What should have been a routine operational day deteriorated into bottlenecks, constraint violations, recovery pressure, and dissatisfied customers. Not because systems failed, but because reality moved faster than the intelligence designed to observe it.

While analytics platforms continued to display green indicators, and AI-assisted scheduling tools reported plans within tolerance, none of them detected the spark that lit the fire. Each system accurately described its own slice of the operation, yet none understood how the operation was actually evolving. The moment that mattered passed unnoticed.

This pattern is not unique to ports. The same failure mode appears in road traffic through major ferry terminals, in delayed inbound flights cascading across airport networks, and in offshore wind farms where weather-driven maintenance slips compress access windows and propagate through crew availability, vessel schedules, and energy output commitments. Different domains, identical outcome. The underlying issue is structural.

Operations do not exist in isolation. They are living systems composed of assets, people, rules, constraints, and external forces, all interacting across space and time. Decisions made in one place reshape the operating conditions elsewhere, often with delay, often invisibly. Yet the analytics and AI tools operators rely on are built as if the world were static, separable, and slow to change.

As soon as the vessel reduced speed, the operational reality of the port changed. Not incrementally, structurally. Slack was removed. Margins collapsed. Previously independent plans became coupled. What followed was not a single failure, but a sequence of locally rational decisions interacting in ways no system was reasoning about.

The disruption did not emerge because something went wrong. It emerged because nothing was watching how reality itself was shifting. This is the gap Unified Intelligence exists to close. Operational failure in complex systems occurs when reality changes faster than intelligence can update.



Unified Intelligence, a new category

The failure of existing approaches is not accidental. It is inevitable, given how operational intelligence has been assembled. As outlined in the first chapter, what is commonly labelled 'operational' or 'decision' intelligence is not a single capability, but a stack of layers, each solving a specific class of problem. Thinking in terms of layers of a stack matters, because each one feeds the next, and therefore naturally becomes entangled and harder to define. We spoke earlier about the variety of technologies in play, but to fully understand how Unified Intelligence compares, we must explore each layer of the stack.

Data integration & semantic formation: At the base of the stack sits data integration and semantic formation. The problem this layer addresses is real: operational data is fragmented, siloed, and difficult to query. Platforms such as Databricks, Snowflake, and Palantir Foundry have made significant progress here, enabling organisations to unify data into a coherent, queryable structure. However, this layer stops short of intelligence. The data is typically batch-ingested rather than live. The resulting view is descriptive, not dynamic. Dashboards built on top of it show what has happened, not how the operation is currently evolving. Forecasts derived from this data project forward from historical patterns, assuming continuity with the past. As soon as reality deviates, a vessel slows unexpectedly, weather shifts, a human intervenes, this layer becomes stale. It does not break, but it silently falls behind.

Analytics and AI models: The next layer introduces AI, most commonly in the form of machine-learning or rules-based models. These models are valuable. They identify patterns, improve forecasts, and outperform simple heuristics or averages. In operational environments where data is sparse, rules-based models encode hard-won expert knowledge and perform essential functions. But these models are inherently bounded. Each model is designed to predict a specific aspect of the operation: an ETA, a demand curve, a weather window, a risk score. They operate within tightly defined scopes and assumptions. Their outputs are typically surfaced as numbers on a screen, predictions detached from the broader operational context.

When reality shifts, these models often remain technically 'correct' while becoming operationally irrelevant. They do not understand how their outputs interact with other constraints, decisions, or human actions elsewhere in the system.

Planning, optimisation, and Digital Twins:

Above analytics sit planning and optimisation tools, including most traditional Digital Twin technologies. These systems combine data and predictions to optimise schedules, resource allocation, and workplans under defined constraints. They are powerful within their design envelope. Crucially, that envelope assumes deliberation. These tools are well suited to strategic and transformational decisions, where scenarios can be explored, assumptions adjusted, and outcomes reviewed. In live operations, however, they rely heavily on human input: someone must notice a deviation, decide to intervene, update assumptions, and rerun the plan. As operational tempo increases, this interaction model breaks down. Plans remain mathematically valid while becoming operationally misaligned. Optimisation does not fail; it simply optimises the wrong version of reality.

Agents and copilots: The next layer introduces agents and copilots. By leveraging LLMs, these tools make data, models, and workflows more accessible. Operators can query across systems, synthesise information, and execute tasks more efficiently. This is a genuine improvement in usability, but not a solution to the core problem. Agents and copilots are reactive by design. They require an operator to know what to ask. If an emerging consequence is not yet visible, no one thinks to prompt an AI. The most important moments are therefore the least likely to be interrogated.

Across all these layers, the same dependency exists: intelligence is only produced when a human interacts with the system. In live operations, this is precisely where failure occurs. Events unfold faster than humans can observe, interpret, and query. More importantly, early signals often appear insignificant in isolation. The event may be noticed, but its downstream consequences remain hidden.

As demonstrated in the opening example, the operation does not fail because data is missing or models are inaccurate. It fails because no system is continuously reasoning about how reality itself is changing.

What is required in these scenarios is, perhaps, more uncomfortable: **Intelligence that exists without being asked for.**



Always on intelligence.

If intelligence only exists when humans look for it, then in live operations intelligence will always arrive too late.

A report from the Massachusetts Institute of Technology found that 95% of enterprise AI projects fail to move from pilot to production. The reasons cited are familiar: misalignment with real business problems, internal builds struggling compared to vendor-led solutions, and a heavy concentration of effort in sales and marketing functions with limited operational return.

But these explanations stop short of the deeper issue. The real failure is not technological or organisational. It is existential. The question most AI projects never answer is how intelligence is supposed to exist within a live operation.

In the opening example, the root cause of failure was a non-obvious deviation: a small change in vessel speed that triggered a cascading sequence of impacts later in the day. No individual operator saw it in time. No system flagged it. Dashboards remained green because each tool observed its own slice of reality in isolation. The failure emerged across the system, not within any single component.

This exposes a structural flaw in how intelligence is delivered today. Most AI systems require prompting. Intelligence is therefore provided only when it is asked for. The same is true of planning and optimisation tools: they require interaction to surface insight. That interaction assumes a human has already recognised that something is wrong.

This assumption is fatal in dynamic systems. If an operator knows to ask, the value of the intelligence has already decayed. The most valuable intelligence exists before awareness, when the signal is weak, the impact is distant, and the problem is still shapeable.

The concept of always-on intelligence resolves this misalignment. It does not wait to be asked. It exists continuously, precisely because in complex, fast-moving systems, the most

important changes occur before anyone knows to look.

Always-on refers to far more than notifications. It describes a continuously maintained intelligence layer: a dynamic operational web that updates as new data arrives. Live signals feed models, predictions adjust in real time, and events propagate through a federated network of Micromodels anchored in a shared ontology. Intelligence is not produced in episodes, it is sustained as a living, evolving understanding of the system.

Removing noise.

The greatest risk of always-on intelligence is not technical complexity, but overload. A system that continuously monitors an operation will detect countless deviations, correlations, and anomalies. If every change produces an alert, intelligence collapses into noise. Operators disengage. Trust erodes. The system is muted or ignored, and the very capability designed to prevent failure becomes part of the problem.

For intelligence to be effective, it must do more than observe. It must exercise judgement. This means reasoning about relevance, criticality, and consequence. Not every deviation matters. Not every signal deserves attention. Intelligence must determine who needs to know, when they need to know, and what level of intervention is justified. Information must be filtered, contextualised, and prioritised before it reaches a human.

This judgement must be sophisticated and grow over time. What matters depends on operational state, proximity to thresholds, compounding risk, and how consequences are likely to propagate. A minor deviation in one context may be irrelevant; the same deviation in another may be systemically dangerous. Always-on intelligence succeeds only when it reduces cognitive load

rather than increasing it. Its value lies not in surfacing more information, but in deciding what not to surface. Signal emerges when noise is actively suppressed. Without this capability, continuity becomes liability. With it, continuous intelligence becomes usable, trusted, and operationally decisive.

To determine what matters and what does not, intelligence must understand more than thresholds or isolated metrics. It must maintain a live awareness of where the operation is in space and time, how close it is to critical boundaries, and how small changes can compound into system-wide effects.

In complex operations, meaningful failure rarely originates as a large, obvious event. It emerges when minor deviations propagate through tightly coupled systems, interacting with constraints, human decisions, and timing in ways that are invisible in isolation. Identifying these trajectories requires intelligence that reasons about propagation, not just detection. This capability is known as cascading impact reasoning. It is not an enhancement; it is foundational.

Understanding cascading impacts.

Cascading impact reasoning understands how events propagate through an operational network and continuously evaluates how events alter the live operational state and how those

alterations influence adjacent assets, processes, and decisions over time. Events are captured as they occur. Local models update continuously. A reasoning layer evaluates second and third-order effects across the system.

- If a vessel arrives late, what downstream berth movements are affected?
- If a road incident occurs, how does traffic displacement evolve over the next hour?
- If a weather window narrows, which crews, assets, and commitments are at risk?

These are not one-off analyses. They are ongoing, stateful workflows that must execute continuously, without human prompting. The intelligence cannot wait for an operator to ask what the impact might be, because by the time the question is formed, the window to intervene has often passed.

Cascading impact reasoning, combined with selective filtering and prioritisation, is what transforms continuous monitoring into usable intelligence. It allows the system to surface only those developments that are likely to matter, to the right people, at the right moment. Without this capability, always-on systems generate noise. With it, they generate foresight.

But what about the data?

We have come a long way in this paper without explicitly addressing one of the most critical prerequisites for Unified Intelligence: access to data. Without data, intelligence cannot exist.

One of the enabling forces behind Unified Intelligence, as described earlier, is the apparent abundance of data now available. Operational environments are increasingly instrumented. Sensors are proliferating. Digital systems capture more detail than ever before. Awareness of data's value has grown. All of this is true. Yet in real operational contexts, the data required to understand how systems behave rarely sits within a single organisation. It spans ecosystems of operators, partners, suppliers, and regulators. The question is therefore not whether data exists, but whether it will be shared.

Data sharing is not a new discussion. It is often framed in terms of infrastructure, interoperability, governance, security, and legal mechanisms. These are essential considerations. Any Unified Intelligence capability must be built on robust data-sharing foundations that allow information to be secured, segmented, permissioned, and governed appropriately across organisational boundaries. Without this, trust and safety are compromised. But these mechanisms, while necessary, are not sufficient.

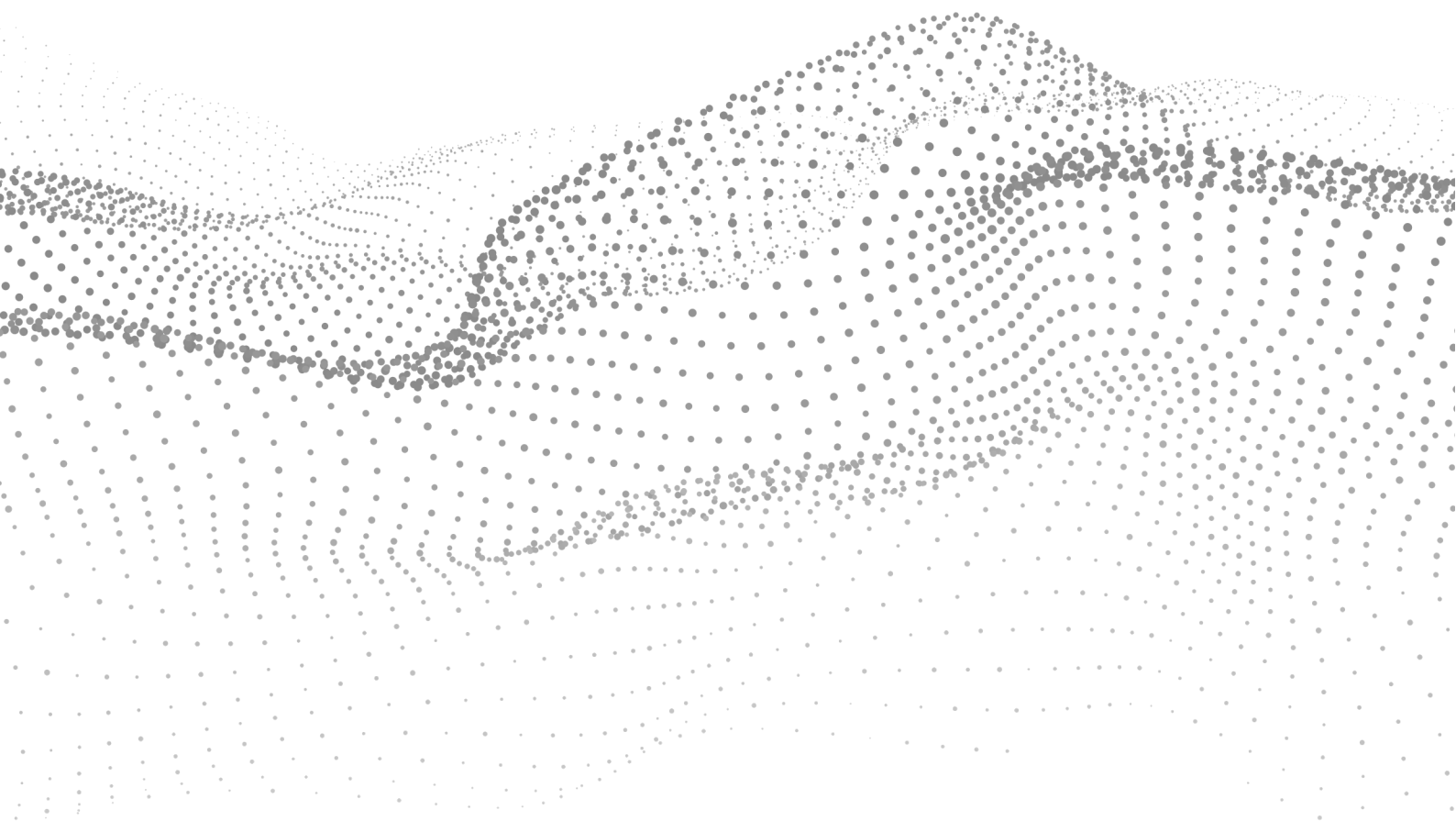
Data is not shared because it can be. It is shared because doing so creates value. Simply exposing data is not a benefit. Value only emerges when shared data leads to better decisions, decisions that could not have been made otherwise, and outcomes that materially improve performance, safety, or resilience.

This is where many existing approaches struggle. They begin with the assumption that intelligence is strategically important, then immediately focus on 'unlocking' data sharing as the primary challenge. The conversation quickly moves into abstract, sensitive territory, negotiating hypothetical future value without any tangible proof. The 'so what' is deferred.

Seeing is believing. Believing is seeing.

Unified Intelligence reverses this dynamic. As we discuss in the next chapter, it is designed to be deployed iteratively, starting with a narrow, high-consequence substrate of the system. It does not require perfect data coverage across the entire ecosystem from day one. By design, it grows and expands as data becomes available. Early deployments demonstrate real, observable intelligence: foresight that changes decisions and alters outcomes.

This shifts the data-sharing conversation from abstraction to reality. Intelligence is no longer promised; it is shown. Stakeholders can see the value being created. They can observe decisions being made earlier, risks being avoided, and coordination improving. Trust is earned through demonstrated impact, not hypothetical upside. The conversation of data sharing becomes quid pro quo.



In this way, Unified Intelligence creates a pull for data sharing. Proven intelligence leads to belief. Belief leads to participation. Participation expands data availability, which in turn strengthens the intelligence.

For Unified Intelligence to be realised, data must be shared. But for data to be shared at scale, intelligence must be proven first. The sequence matters. Unified Intelligence succeeds by putting realised understanding at the front and letting data sharing follow through action.

Unification compounds insight.

A common concern in data-driven initiatives is whether there is 'enough' data. Organisations invest significant time and effort defining taxonomies, cataloguing sources, and performing exhaustive analysis to achieve completeness before intelligence can begin. This instinct is understandable, but it is also misplaced.

Unified Intelligence does not emerge fully formed. Like any living system, it grows. As it grows, its data requirements evolve. Information that appears marginal or irrelevant today may become critical as the operational context changes or as new patterns of behaviour emerge. Attempting to define all future data needs in advance is not only impractical, it delays value.

More importantly, unification changes the nature of data itself. When disparate data sources are connected within a shared operational frame of reference, new information is created. This is derived data: insights that do not exist in any single source but emerge from their combination. Raw observations become meaningful only when they are placed in context, anchored in space, time, assets, constraints, and relationships.

Derived data is where compounding value begins. As more of the operation is unified, the intelligence does not improve linearly. It deepens. New dependencies become visible. Latent constraints surface. Early signals that were previously indistinguishable from noise acquire meaning. Insight compounds because understanding expands. This is why Unified Intelligence benefits from iteration rather than completeness. Each step of unification not only consumes data, but produces new understanding that reshapes what data matters next.